Numerical Analysis — FMN011 — 2015/06/03

The exam lasts 4 hours and has 14 questions. A minimum of 35 points out of the total 70 are required to get a passing grade. These points will be added to those you obtained in your two home assignments, and the final grade is based on your total score.

Justify all your answers and write down all important steps. Unsupported answers will be disregarded.

During the exam you are allowed a pocket calculator, but no textbook, lecture notes or any other electronic or written material.

1. (5p) What vector norm should I use in each of the following cases?
   (a) Calculate the distance I need to walk to go from Lund’s cathedral to Lund’s library.
   (b) Calculate the height of a door so that every person under 1.4 meters can pass under it without bending down.
   (c) Calculate the magnitude of the residual after fitting a straight line to given data, using least squares.
   (d) Make sure that the values of an error vector are all under $10^{-3}$.
   (e) Calculate how many squares a rook needs to move over to get to a specific position on the chessboard (may require more than one move).

   ![Figure 1](https://via.placeholder.com/150)

   Figur 1: These are the possible positions of a rook after a single move.

2. (5p) I need to solve the following equation for $x$:

   $$x - \frac{1}{2} y = \frac{h(x) + h(y)}{20}$$

   where $y = 1$ and $h(x) = x^5$. Choose one of the following methods and write out the iteration I must perform for this particular problem (in detail). Do not solve.
   (a) $x_{n+1} = x_n - f(x_n)/f'(x_n)$
   (b) $x_{n+1} = Ax_n$
   (c) $x_{n+1} = g(x_n)$
3. (4p) After solving a problem with 7 iterations of a certain iterative method, I get the following errors:

\[
\begin{align*}
0.6 & \quad 0.54 & \quad 0.45 & \quad 0.3 & \quad 0.14 & \quad 0.028 & \quad 0.0012
\end{align*}
\]

Calculate what is the rate of convergence of the method, with the help of

\[
\|e_{k+1}\| \leq c \cdot \|e_k\|^r
\]

4. (6p) Explain what the backslash operator in Matlab does (what method does it use, what particular features) when we write the command \(x = A\backslash b\), and

(a) \(A\) is a full \(15 \times 15\) matrix
(b) \(A\) is a \(150 \times 5\) matrix
(c) \(A\) is an upper triangular matrix of dimension \(25 \times 25\).

5. The projection of a vector \(v\) onto a vector \(w\) is

\[
\text{proj}_w v = \frac{v^t w}{w^t w} w.
\]

(a) (2p) Construct an orthogonal basis for the subspace spanned by vectors \((1, 1, 0)\) and \((2, 0, 3)\).
(b) (2p) What is the relation between the basis you constructed and the QR factorization of \(A\)?

6. (6p) Let \(A\) be an invertible \(n \times n\) real matrix.

(a) Prove that the eigenvalues of \(A\) and \(A^T\) are the same. (Hint: we know that \(\det(A) = \det(A^T)\).)
(b) Prove that if \(\lambda\) is a non-zero eigenvalue of \(A\) then \(1/\lambda\) is an eigenvalue of \(A^{-1}\).
(c) Prove that if \(A\) is an orthogonal matrix, its real eigenvalues are \(\pm 1\).

7. (5p) Comment on the following statements:

(a) There is one unique polynomial of degree \(n\) that interpolates \(n\) data points.
(b) Interpolation is usually not appropriate if the data points are subjected to experimental errors.
(c) When doing high-degree polynomial interpolation the curve may wiggle so much that it will not pass through all the data points.
(d) Chebyshev interpolation points are bunched near the center of the interval.
(e) A spline is a piecewise polynomial of degree \(k\) that is continuously differentiable \(k\) times.

8. (5p) Give two examples of additional conditions that might be imposed to determine the cubic spline interpolant to a set of data points.

9. (6p) After applying a QR iteration to each of two matrices, \(A\) and \(B\), the results are, respectively:
\begin{align*}
\text{ans} &= \\
&= \begin{pmatrix} 4.8979 & -1.5046 \times 10^{-16} & -3.5827 \times 10^{-16} & -2.7318 \times 10^{-16} \\
& 0 & 0.60394 & 2.8797 \times 10^{-16} & -7.0097 \times 10^{-16} \\
& 0 & 0 & 0.14022 & -7.0097 \times 10^{-16} \\
& 0 & 0 & 0 & 0.00041375 \end{pmatrix} \\
\text{and} \\
\text{ans} &= \\
&= \begin{pmatrix} -3.0025 & 0.24446 & -3.663 & 1.2072 \\
& 0 & 0.51801 & 0.025815 & 0.32126 \\
& 0 & 0 & -0.21637 & 0.071929 \\
& 0 & 0 & 0 & -0.00050994 \end{pmatrix}
\end{align*}

One of the original matrices is real symmetric. Which one is it, and how can you tell?

10. (5p) Count the number of operations involved in carrying out \( k \) steps of the unnormalized power method \( x_{i+1} = Ax_i \) for an \( n \times n \) matrix.

11. (4p) The DFT of a real vector of length \( n \) can be interpreted as interpolation by a set of \( n \) trigonometric basis functions.

   (a) Why does computing the DFT not require the solution of an \( n \times n \) linear system by matrix factorization in order to determine the coefficients of the basis functions?

   (b) What is the worst-case computational complexity for computing the DFT? For what values of \( n \) is this the case?

   (c) What is the best-case computational complexity for computing the DFT? For what values of \( n \) is this the case?

   (d) Explain briefly the reason for the difference, or the lack of it, between the complexities in parts \( b \) and \( c \).

12. (5p) Use Huffman coding to construct a code for the elements of the following matrix.

\[
\begin{pmatrix}
5 & 3 & 2 & 2 \\
3 & 4 & 1 & 1 \\
1 & 4 & 0 & 0 \\
0 & 0 & 0 & 0
\end{pmatrix}
\]

13. (5p) Let \( A \) be an \( m \times n \) real matrix, and

\[
\begin{pmatrix} 0 & A^t \\ A & 0 \end{pmatrix} \begin{pmatrix} u \\ v \end{pmatrix} = \lambda \begin{pmatrix} u \\ v \end{pmatrix}
\]

Show that \(|\lambda|\) is a singular value of \( A \).

14. (5p) Mention and briefly describe the different types of compression that are used in JPEG.

C. Arévalo